



ΘΕΜΑ Α

- A1. β
A2. δ
A3. β
A4. α
A5. α. Λάθος
β. Σωστό
γ. Σωστό
δ. Λάθος
ε. Λάθος

ΘΕΜΑ Β

B1.α. Σωστή απάντηση i.

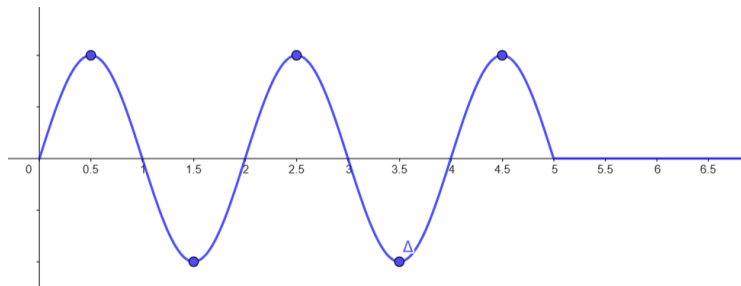
B1.β. $\phi = 2\pi \left(\frac{t}{T} - \frac{x}{\lambda} \right) \Rightarrow \phi = 2\pi \left(\frac{2}{T} - \frac{x}{\lambda} \right)$

$x=0: \phi = \frac{4\pi}{T} \Rightarrow 4\pi = \frac{4\pi}{T} \Rightarrow T=1s$

$\phi=0: 0 = 2\pi \left(\frac{2}{1} - \frac{x}{\lambda} \right) \Rightarrow 0 = 2 - \frac{4}{\lambda} \Leftrightarrow \frac{4}{\lambda} = 2 \Leftrightarrow \lambda = 2m$

$u_{\delta} = \frac{\lambda}{T} = 2m/s$

$t_2 = 2,5s: x = u_{\delta} t = 2 \cdot 2,5 = 5m = 2\lambda + \frac{\lambda}{2}$



5 σημεία

B2. ii. $f(1) = \frac{\phi}{h}$.

$$K = h \cdot f_2 - \phi \Leftrightarrow e \cdot V_0 = h \cdot 3 \cdot f_1 - f_1 \cdot h \Leftrightarrow V_0 = \frac{2 \cdot h \cdot f_1}{e}$$

B3.α. ii. $\vec{U}_{\sigma\alpha\theta} \Rightarrow F_{\mu\alpha\gamma} = F_{\eta\lambda} \Leftrightarrow B_1 \cdot u \cdot q = E \cdot q$

$$u = \frac{E}{B_1}$$

B3.β. i. $d_2 - d_1 = d \Leftrightarrow 2R_1 - 2R_2 = d \Leftrightarrow \frac{m_1 \cdot u}{B_2 \cdot q} - \frac{m_2 \cdot u}{B_2 \cdot q} = \frac{d}{2}$

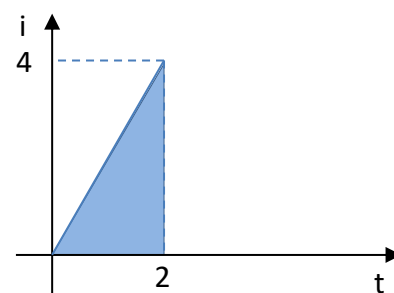
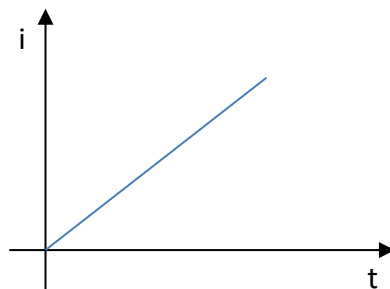
$$m_1 - m_2 = \frac{\frac{d}{2}}{\frac{1}{B_2 \cdot q}} \Leftrightarrow m_1 - m_2 = \frac{d \cdot B_2 \cdot q}{2 \cdot u} = \frac{d \cdot B_2 \cdot q}{2 \cdot \frac{E}{B_1}} = \frac{d \cdot B_1 \cdot B_2 \cdot q}{2E}$$

ΘΕΜΑ Γ

Γ1. $\frac{\Delta i}{\Delta t} = \frac{\Delta(2t)}{\Delta t} = 2 \text{ A/s}$

$$i = 2 \cdot 2 = 4 \text{ A}$$

$$q = E = \frac{2 \cdot 4}{2} = 4 \text{ Cb}$$



Γ2. Αφού $\frac{\Delta i}{\Delta t} > 0$, δηλαδή $i \uparrow$ λόγω κανόνα Lenz.

Πολικότητα στο πηνίο + A, -Γ

$$|F_{\text{ΑΥΤ}}| = \left| -L \frac{\Delta i}{\Delta t} \right| = 0,5 \cdot 2 = 1 \text{ V}$$

Γ3. $i = \frac{E_{\text{ΕΠ}} - |E_{\text{ΑΥΤ}}|}{R_{\text{ΟΛ}}} = \frac{Bv - |E_{\text{ΑΥΤ}}|}{R_{\text{ΟΛ}}}$

$$2t = \frac{1 \cdot v \cdot 1}{1} \Leftrightarrow 2t = v - 1 \Leftrightarrow v = 2t + 1 \quad (\text{SI})$$

$$\Gamma 4. \alpha. \quad \alpha = \frac{\Delta v}{\Delta t} = 2 \text{ m/s}^2$$

$$\Sigma \vec{F} = m \cdot \vec{a} \Rightarrow F - F_1 - w = m\alpha \Rightarrow F = F_1 + m\alpha + mg = BIl + m\alpha = 1 \cdot 2t \cdot 1 + 0,5 \cdot 2 + 5$$

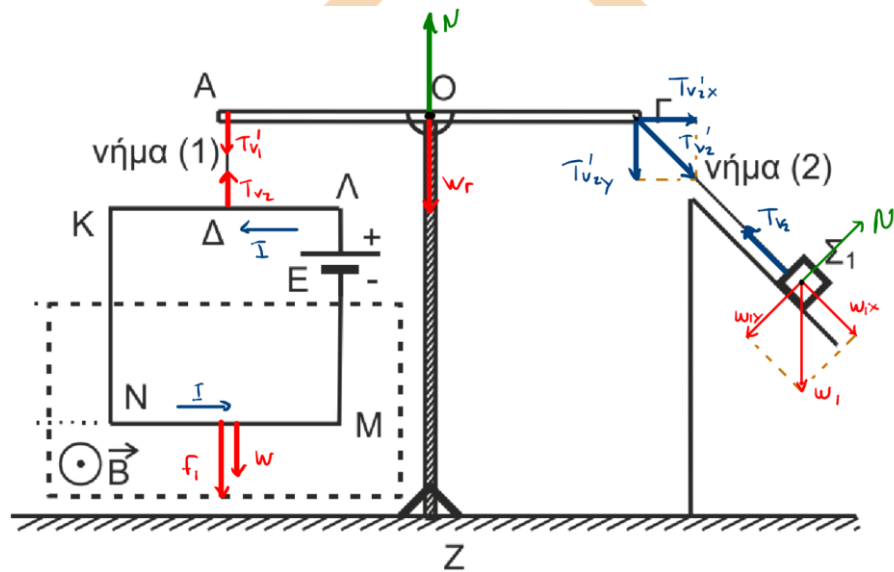
$$t = 2 \text{ s} : F = 10 \text{ N}$$

$$\Gamma 4. \beta. \quad P_F = \frac{\Delta W_F}{\Delta t} = F \cdot v, \quad v = 2t + 1 = 5 \text{ m/s}, \quad P_F = 50 \text{ J/s}$$

$$\Gamma 4. \gamma. \quad \frac{\Delta U_L}{\Delta t} = E_{\text{ΑΥΤ}} \cdot i = 1 \cdot 4 = 4 \text{ J/s}$$

$$i = 2t = 2 \cdot 2 = 4 \text{ A}$$

ΘΕΜΑ Δ



$$\Delta 1. \quad \Sigma_1 : \Sigma \vec{F}_x = 0 \Rightarrow m_1 g \eta \mu \phi = T_{v2} \Rightarrow T_{v2} = 3 \cdot 10 \cdot \frac{3}{5} \Rightarrow T_{v2} = 18 \text{ N}$$

$$T'_{v2} = T_{v2} = 18 \text{ N}$$

$$\text{Ράβδος: } \Sigma \vec{\tau}_{(O)} = 0 \Rightarrow \tau_{T'_{v1}} = \tau_{T'_{v2y}} \Rightarrow T'_{v1} \frac{l}{2} = T'_{v2y} \frac{l}{2} \Rightarrow T'_{v1} = \eta \mu \phi T'_{v2} = \frac{3}{5} 18 = 10,8 \text{ N}$$

$$\Delta 2. \quad T_{v1} = T'_{v1} = 10,8 \text{ N},$$

$$I = \frac{E}{R_{\pi\lambda}} = \frac{30}{2} = 15 \text{ A}$$

$$\text{πλαίσιο: } \Sigma F_y = 0 \Rightarrow w + F_L = T_{v1} \Rightarrow T_{v1} = F_L = B l \alpha \Rightarrow B = \frac{T_{v1}}{l \alpha} = \frac{10,8}{15 \cdot 0,8} = 0,9 \text{ T}$$

$$\Delta 3. \quad \Sigma_2: v_{2\max} = \omega_2 d = \sqrt{\frac{k}{m_2}} d = 10 \frac{9\pi}{100} = \frac{9\pi}{10} \text{ m/s}$$

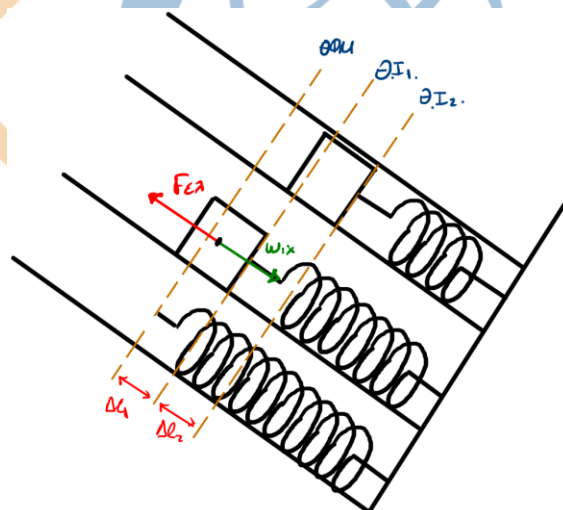
$$\Sigma_1: \Sigma F_{1x} = w_{1x} \Rightarrow m_1 \alpha = m_1 g \eta \mu \phi \Rightarrow \alpha = g \eta \mu \phi = 10 \frac{3}{5} = 6 \text{ m/s}$$

$$\omega_2 = \sqrt{\frac{k}{m}} = 10 \text{ rad/s}, \quad T = \frac{2\pi}{\omega} = \frac{2\pi}{10} = \frac{\pi}{5} \text{ s}, \quad \Delta t = \frac{T}{4} = \frac{\pi/5}{4} = \frac{\pi}{20} \text{ s}$$

$$v_1 = \alpha_1 \Delta t = 6 \frac{\pi}{20} = \frac{3\pi}{10} \text{ m/s}$$

$$\text{ΑΔΟ: } m_2 v_{2\max} - m_1 v_1 = (m_1 + m_2) v_o \Rightarrow v_o = \frac{m_2 v_{2\max} - m_1 v_1}{(m_1 + m_2)} = \frac{1 \cdot \frac{9\pi}{10} - 3 \cdot \frac{3\pi}{10}}{4} = 0$$

$\Delta 4.$



$$(1) \quad m_2 g \eta \mu \phi = k \Delta l_1 \Rightarrow \Delta l_1 = \frac{m_2 g \eta \mu \phi}{k} = \frac{1 \cdot 10 \cdot \frac{3}{5}}{100} = 0,06 \text{ m}$$

$$(2) \quad (m_1 + m_2) g \eta \mu \phi = k(\Delta l_1 + \Delta l_2) \Rightarrow$$

$$\Delta l_1 + \Delta l_2 = \frac{(m_1 + m_2) g \eta \mu \phi}{k} = \frac{4 \cdot 10 \cdot \frac{3}{5}}{100} = 0,24 \text{ m}$$

$$\Delta l_2 = 0,18 \text{ m} = A$$

$$\omega' = \sqrt{\frac{k}{m_1 + m_2}} = 5 \text{ rad/s}$$

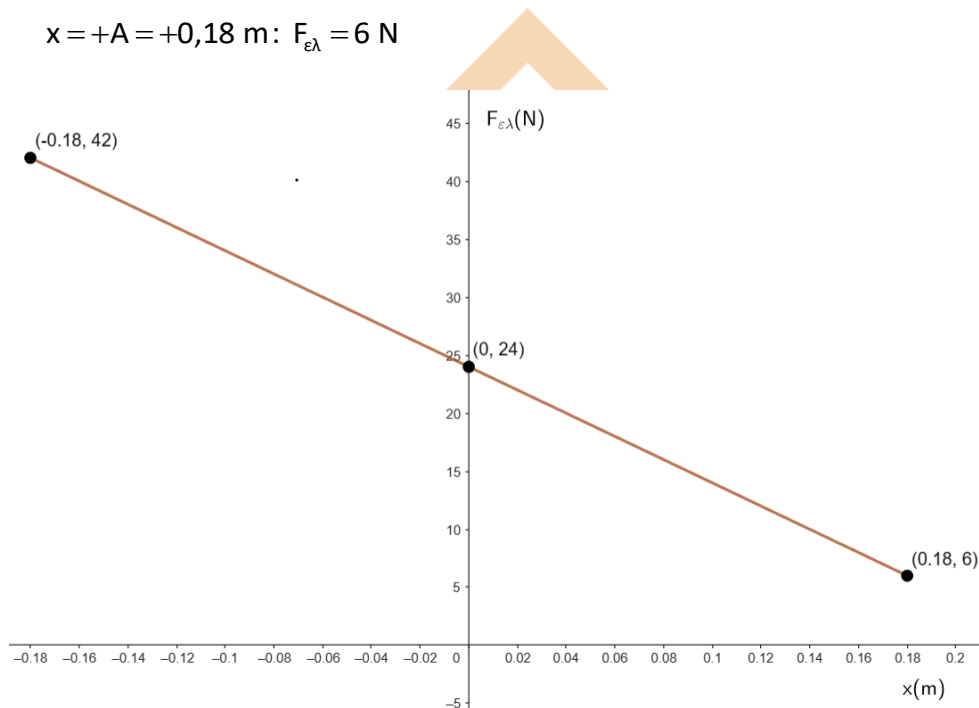
$$x = A \eta\mu(\omega t + \phi) = 0,18 \eta\mu\left(5t + \frac{\pi}{2}\right) (\text{SI})$$

Δ5. $F_{ελ} = (m_1 + m_2) g \eta\mu\phi - k x = 24 - 100x \text{ (SI)}$

$x = 0: F_{ελ} = 24 \text{ N}$

$x = -A = -0,18 \text{ m}: F_{ελ} = 42 \text{ N}$

$x = +A = +0,18 \text{ m}: F_{ελ} = 6 \text{ N}$



ΟΡΟΣΗΜΟ